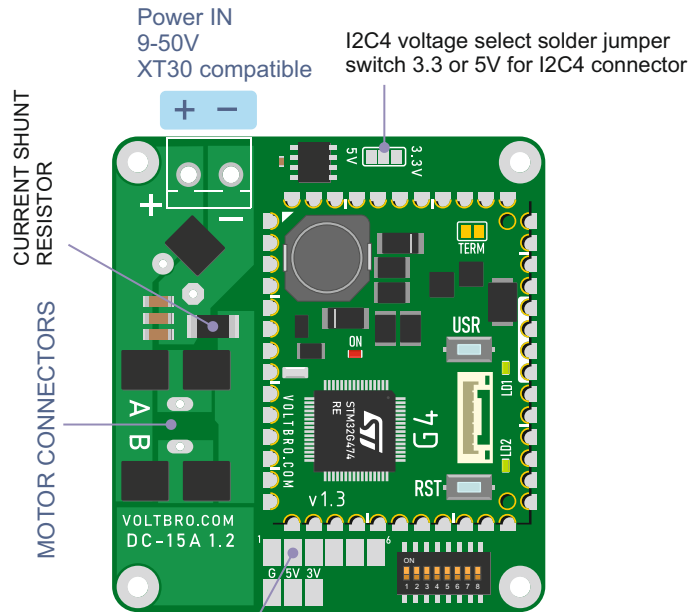
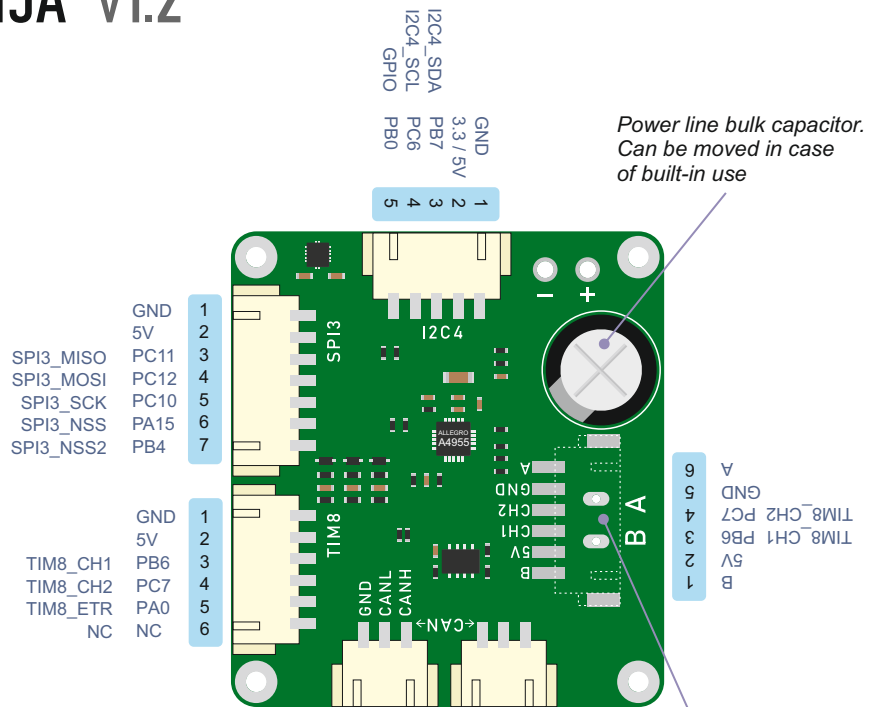


VBCore DC motor Driver 15A v1.2



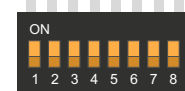
Solder pads
Use common pins with user switch (1-6 inputs)
NOTE: put switches off in case of using solder pads



TIM8 for quadrature encoder
AB 2-Channel / ABZ 3-Channel

User switch

8 pin, ON == HIGH



PB10
PB11
PB12
PB13
PB14
PB15
PC8
PC9

VBCore DC motor Driver v1.2

VIN: 9-50V
MAX CURRENT: 15A
MCU: VB32G4 (STM32G474RE)
DRIVER: ALLEGRO A4955
SPI interface
ABZ encoder interface
I2C interface
Current control
I2C EEPROM
CAN / CAN-FD
Dimensions: 51x56mm
Mount holes: 45x50mm D2.5 mm

NOTES:

1. SPI3 connector connected to controller via level shifters
2. Hall sensors connectors connected to controller via filter
3. I2C4 SCL and SDA lines pulled up - **DON'T USE** internal pull-up
4. I2C4 line (including EEPROM) is powered through solder bridge

VBCores

www.vbcores.com
Electronics for robotics
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Driver

Allegro A4955, 50 V
Full-Bridge PWM Gate Driver
designed for control of DC motors

Controll	PIN	Notes
SLEEPn	PB3	
IN1	PA8	TIM1_CH1
IN2	PA9	TIM1_CH2
AIOU	PC1	
VREF	PA4	1:2 divider
FAULT	PB5	
RC		$R_{RC} = 47K, C_{RC} = 1n$
ISET		$R_{ISET} = 47K$
SENSE		$R_{SENSE} = 0,01$

EEPROM

256K
AT24C256C

Controll	PIN	I2C
A0	GND	
A1	GND	
A2	GND	
SCL	PC6	I2C4_SCL
SDA	PB7	I2C4_SDA

Voltage controll

Resistive voltage divider 16:1

Controll	PIN	ADC
V input	PC0	ADC12_IN6

Current shunt resistor

Connected to A4955 driver

Size	Default
1206	$R_{SENSE} = 0.01 \text{ Ohm}$